Time allowed: **55 minutes**. Show **all** your working.

1. [10 marks]

- (a) Let $A = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 2 & 3 & 0 \end{bmatrix}$. Compute e^{tA} , for $t \in \mathbb{R}$. **Hint**: A is nilpotent.
- (b) Suppose that for $t \in \mathbb{R}$, x(t), y(t) and z(t) are given by

$\begin{bmatrix} \dot{x} \\ \dot{y} \\ \dot{z} \end{bmatrix} = \begin{bmatrix} -4 & 0 & 0 \\ 1 & -4 & 0 \\ 2 & 3 & -4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} , \qquad \begin{bmatrix} x(0) \\ y(0) \\ z(0) \end{bmatrix}$	=	$\left[\begin{array}{c} x_0\\ y_0\\ z_0 \end{array}\right]$	
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Using your answer from part (a), derive explicit expressions for x(t), y(t) and z(t) in terms of x_0 , y_0 and z_0 .

- 2. [10 marks] Consider the one-dimensional system, $\dot{x} = \sqrt{|x|}$, x(0) = -1.
 - (a) Compute the solution to the system valid while $x(t) \leq 0$, and show that x(2) = 0.
 - (b) For $t \ge 2$ the solution is not unique. Determine the range of values that are possible for x(3).
- 3. [10 marks] Consider the system

$$\dot{x} = y + (x+3)(x-2) \dot{y} = xy$$

- (a) Find all equilibria.
- (b) Classify each equilibrium as one of: *stable node*, *stable focus*, *unstable focus*, *unstable node*, *saddle*, or *other*.
- (c) Show that the system has a heteroclinic orbit.
- 4. [10 marks] Consider the system

$$\dot{x} = 3x + y + 2xy \dot{y} = 5xy - xy^2$$

- (a) Calculate $W^{c}(0,0)$ to third order.
- (b) Derive an ODE for the dynamics on $W^{c}(0,0)$ to third order.